

# Discussion of "Estimating Nonlinear Heterogeneous Agent Models with Neural Networks " by Hanno Kase, Leonardo Melosi and Matthias Rottner

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- Linearized small-scale DSGE model - can compare to the analytical solution.
- A RANK model with a ZLB - compare with other nonlinear estimation methods.
- A nonlinear HANK model (ZLB + aggregate risk) - **main contribution**.

# Overview: Model Solution

- Treat the estimable parameters  $\tilde{\Omega}$  as **pseudo-state** variables.
- Build **two** networks

$$\psi_t^i = \psi^I(\mathbb{S}_t^i, \mathbb{S}_t, \tilde{\Omega}|\bar{\Omega}) \quad \psi_t^A = \psi^A(\mathbb{S}_t, \tilde{\Omega}|\bar{\Omega})$$

- Where the state vector  $\mathbb{S} \in \{\mathbb{S}^A, \{\mathbb{S}^i\}_{i=1}^L\}$  includes the states of **all** agents  $L$ .
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- Curse of dimensionality
  - Make **draws** from the parameter space *instead* of solving **on the grid** .
  - The relevant share of the state space **shrinks** as the number of state variables  $\uparrow$ .
  - Make draws from the **simulated** model.

# Overview: Model Estimation

$$\mathcal{L}(\mathbb{Y}_{1:T}|\tilde{\Omega}) = \prod_{t=1}^T p_{\tilde{\Omega}} \left( y_t | y_{t-1}, \dots, y_1, \tilde{\Omega} \right)$$

When the model is nonlinear:

- Need to use MC filters, which are time-consuming and less accurate.

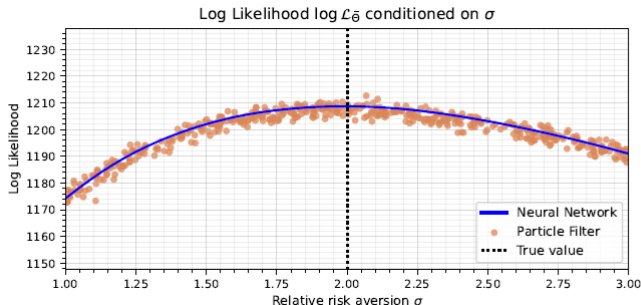
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Instead: Use the ANN to **approximate** the mapping between  $\mathcal{L}(\mathbb{Y}_{1:T}|\tilde{\Omega})$  and  $\tilde{\Omega}$ , dubbed as the ANN *particle filter*. This allows for **fast** and **precise** likelihood evaluation.



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We want a network that **approximates well** BUT allows for a *fast* convergence: 1. **trains fast**, 2. **stable** across iterations.

Stability especially relevant because:

- In the context of model solution, data is *endogenous* to the network weights.
- Every iteration there is a *new* sample draw.
- Any analogies to parameter dampening in the regression?

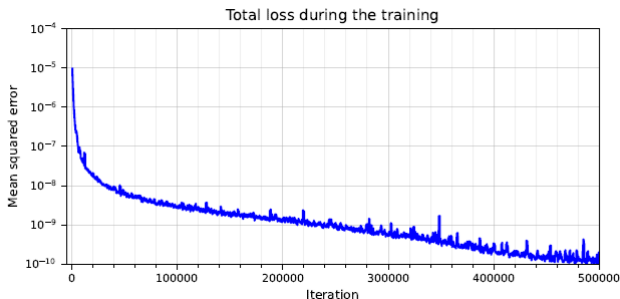
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# Wide or Narrow?

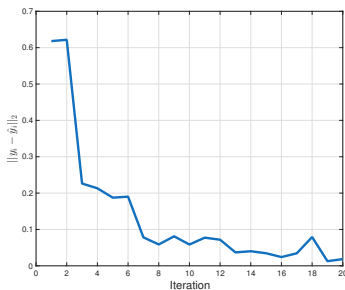
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- Training **narrow** networks is more **efficient**.

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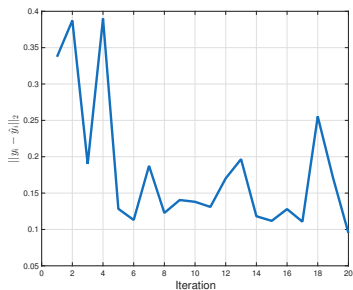
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## Experiment:

- Consider a wide shallow network (27 neurons, 1 layer) and a deep narrow network (9 layers 3 neurons each).
- Each iteration: learn the mapping  $y_i = f(X_i)$  with the new data draws.



(a) Narrow; Av. training time 23s.



(b) Wide; Av. training time 44s.



# Discretization or Moments?

## Discretization

Currently, the model is solved by assuming that the economy consists of a discrete number  $L$  agents:

- Allows to keep track of **all the features** of the **wealth distribution**,
- Requires a **large**  $L$  for a precise solution when the wealth distribution matters,
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## Distribution Moments

Alternatively, one can use **selected moments** of the wealth distribution in  $\mathbb{S}$ .

- Simulate a **histogram** (Young, 2010) and compute **selected moments** as elements of  $\mathbb{S}$ ,
- Potentially **easier** to train the network and converge the algorithm and NOT more costly to simulate,
- **Which** moments to use?
- OR one could use the **histogram** as part of  $\mathbb{S}$ .

# Discretized distribution when individual nonlinearity is relevant

This paper makes significant progress in handling **aggregate nonlinearity**.  
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Additionally:

- Ramsey problems with heterogeneous agents - one needs to keep track of the whole distribution, discrete L does the trick!

Thank You!



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